

# 결합 분포에 기초한 2계 마코비안 도착과정의 생성에 관한 연구

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## Generation of the Markovian Arrival Process of Order 2 Based on Joint Distribution

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In queueing network analysis, the Markovian arrival process, MAP, can be used as approximating arrival or departure processes. While the renewal processes such as Poisson process can be generated based on the marginal moments, the Markovian arrival process requires lag-1 joint moment or joint distribution function. In fact, the Markovian arrival process can be simulated by two transition rate matrices,  $(D_0, D_1)$ , which is called the Markovian representation. However, finding a Markovian representation of higher order involves a numerically iterative procedure due to redundancy in the Markovian representation. Since there is one-to-one correspondence between joint moments and the coefficients of the joint Laplace transform, generating a MAP based on joint distribution can be much less complicated. In this paper, we propose an approach to generate a MAP based on joint distribution function which can be quickly obtained from joint moments and joint Laplace transform. Closed form formula and streamlined procedures are given for the simulation of MAP of order 2.

**Keywords:** Markovian Arrival Process, Moment Matching, Laplace Transform, Lag-1 Joint Distribution Of Intervals

### 1. Introduction

The Markovian arrival process, MAP, can be generated by two transition rate matrices  $(D_0, D_1)$  which is called the Markovian representation. However, finding a Markovian representation of higher order MAP by moment matching is quite complicated due to redundancy of transition rate matrices  $(D_0, D_1)$ . On the other hand, however, the moment matching is straightforward for the Laplace transform (LT) of which minimal representation is known; see Kim (2016) for details. It is well known that the minimal number of parameters for a  $MAP(n)$  is  $n^2$ ; see Bodrog *et al.* (2008), Casale *et al.* (2010) and Telek *et al.* (2007) for details. Since the minimal LT representation is available for the MAP of

any order, the parameters of the LT can be obtained in closed form by moment matching whereas closed - form transformation is not available from moments to the Markovian representation  $(D_0, D_1)$  except for the MAP of order 2, MAP(2); see Bodrog *et al.* (2008), Kim (2017), Ramirez-Cobo *et al.* (2010, 2012) for details.

As for generating or simulating a MAP is concerned, the lag-1 joint distribution can be used instead of the Markovian representation  $(D_0, D_1)$ . A minimal joint LT can be easily converted into a joint distribution by LT inversion. If the inverse LT is not in explicit form of known distribution function, a simple algebraic manipulation can be used to determine exact distribution which is needed for generating a MAP. We are interested in the problem of

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obtaining a simulation - ready joint distribution from the set of minimal moments and minimal joint LT. We focus only on MAP(2) in this paper even though our approach can be generalized to MAP of higher order.

The paper is organized as follows. In Section 2, we review known results on the representation of MAP(2)s. Then, we present main result on the joint distribution of stationary intervals of a MAP(2) by inversion of joint LT in Section 3 followed by the numerical examples given in Section 4. We conclude in Section 5 with discussions on future direction of research.

## 2. Preliminaries

### 2.1 Markovian representation ( $\mathbf{D}_0, \mathbf{D}_1$ )

A MAP(2) is fully described by the two transition rate matrices ( $\mathbf{D}_0, \mathbf{D}_1$ ) given in terms of six rate parameters ( $\lambda_{11}, \lambda_{12}, \lambda_{21}, \lambda_{22}, \sigma_1, \sigma_2$ ), i.e.

$$\mathbf{D}_0 = \begin{bmatrix} -\lambda_1 - \sigma_1 & \sigma_1 \\ \sigma_2 & -\lambda_2 - \sigma_2 \end{bmatrix}, \quad \mathbf{D}_1 = \begin{bmatrix} \lambda_{11} & \lambda_{12} \\ \lambda_{21} & \lambda_{22} \end{bmatrix}$$

where  $(\lambda_1, \lambda_2) = (\lambda_{11} + \lambda_{12}, \lambda_{21} + \lambda_{22})$ . Each off - diagonal rate parameter of  $\mathbf{D}_0$  represents the transition rate out of a given phase into another phase but without invoking an arrival whereas each rate parameter of  $\mathbf{D}_1$  represents the transition rate invoking an arrival with or without changing phase. Let  $\mathbf{Q} = \mathbf{D}_0 + \mathbf{D}_1$  and  $\mathbf{P} = (-\mathbf{D}_0)^{-1}\mathbf{D}_1$ . Then,  $\mathbf{Q}$  is an infinitesimal generator for the continuous time Markov chain whereas  $\mathbf{P}$  is the transition probability matrix for the embedded discrete time Markov chain. Let  $p$  be the stationary probability vector for  $\mathbf{P}$ , i.e.  $p\mathbf{P} = p$  and  $pe = 1$  where  $e$  is a vector of ones.

### 2.2 Moments and the Laplace transform

Let  $T_i$  be the  $i$ -th stationary interval of a MAP. Then, the marginal moments and the lag-1 joint moments are obtained as follows

$$\begin{aligned} E(T_1^k) &= k!p(-\mathbf{D}_0)^{-k}e, \\ E(T_1^k T_2^l) &= k!l!p(-\mathbf{D}_0)^{-k}\mathbf{P}(-\mathbf{D}_0)^{-l}e \end{aligned}$$

respectively. In order to simplify the notation, we use reduced moments defined as

$$\begin{aligned} r_k &= E(T_1^k)/k!, \\ r_{k,l} &= E(T_1^k T_2^l)/(k!l!), \end{aligned}$$

A MAP(2) can be completely described by three marginal moments ( $r_1, r_2, r_3$ ) and one joint moment  $r_{11}$ . In fact, a MAP( $n$ ) is completely described by  $(2n-1)$  marginal moments and  $(n-1)^2$  lag-1 joint moments; see Casale *et al.* (2010) and Telek *et al.* (2007) for a minimal set of moments for MAP( $n$ )s.

It was shown in Kim (2016) that the lag-1 joint Laplace transform (LT) of stationary intervals of MAP( $n$ )s can be written in terms of  $n^2$  parameters. Especially for MAP(2)s, the marginal and lag-1 joint LTs can be written in terms of  $(a_0, a_1, b_1, c_{11})$  as follows

$$\tilde{f}(s) = p(s\mathbf{I} - \mathbf{D}_0)^{-1}\mathbf{D}_1e = \frac{b_1s + a_0}{s^2 + a_1s + a_0} \quad (2.1)$$

$$\begin{aligned} \tilde{f}(s,t) &= p(s\mathbf{I} - \mathbf{D}_0)^{-1}\mathbf{D}_1(t\mathbf{I} - \mathbf{D}_0)^{-1}\mathbf{D}_1e \\ &= \frac{c_{11}s + a_0b_1(s+t) + a_0^2}{(s^2 + a_1s + a_0)(t^2 + a_1t + a_0)} \end{aligned} \quad (2.2)$$

where  $(a_0, a_1, b_1, c_{11}) = (|-\mathbf{D}_0|, \text{Trace}(\mathbf{D}_0), p\mathbf{D}_1e, p\mathbf{D}_1^2e)$ . A MAP(2) can be completely described by Eq. (2.2) which is given in terms of four coefficients  $(a_0, a_1, b_1, c_{11})$ .

### 2.3 Jordan Representation

Another minimal representation used in our study is the Jordan representation given in two matrices ( $\mathbf{E}, \mathbf{R}$ ); see Telek *et al.* (2007) and Kim (2020) for details. A MAP( $n$ ) can be represented by two  $n \times n$  matrices ( $\mathbf{E}, \mathbf{R}$ ) given in terms of  $n^2$  parameters. The diagonal entries of the matrix  $\mathbf{E}$  are eigenvalues of  $(-\mathbf{D}_0)^{-1}$ . The matrix  $\mathbf{R}$  accounts for lag-1 correlation and satisfies  $\mathbf{R}e = e$ ; see Telek *et al.* (2007) for details.

For a MAP(2), let  $(\nu_1, \nu_2)$  be the eigenvalues of  $(-\mathbf{D}_0)^{-1}$  with  $\nu_1 \geq \nu_2$ . For the case of distinct eigenvalues,  $(\mathbf{E}, \mathbf{R})$  can be written in terms of  $(\nu_1, \nu_2, \nu_3, \nu_4)$ , i.e.

$$\mathbf{E} = \begin{bmatrix} \nu_1 & 0 \\ 0 & \nu_1 \end{bmatrix}, \quad \mathbf{R} = \begin{bmatrix} 1 - \nu_3 & \nu_3 \\ \nu_4 & 1 - \nu_4 \end{bmatrix}$$

If  $\nu_1 = \nu_2$ , the  $\mathbf{E}$  is written as

$$\mathbf{E} = \begin{bmatrix} \nu_1 & 0 \\ 0 & \nu_1 \end{bmatrix}.$$

The marginal moments and the lag-1 joint moments are obtained as

$$(r_1, r_2, r_3, r_{11}) = (v\mathbf{E}e, v\mathbf{E}^2e, v\mathbf{E}^3e, v\mathbf{E}\mathbf{R}\mathbf{E}e),$$

where  $v = (\nu_4/(\nu_3 + \nu_4), \nu_3/(\nu_3 + \nu_4))$ . Again, by matching moments  $(\nu_1, \nu_2, \nu_3, \nu_4)$  can be determined by  $(r_1, r_2, r_3, r_{11})$ .

### 3. Joint Distribution and Lag-1 Conditional Distribution

In this section, we propose a new approach in generating a MAP without  $(D_0, D_1)$ . We present closed - form formula for transformation of the joint LT to explicit joint distribution by which stationary intervals are generated.

Since moments can be obtained from the marginal and joint LTs in (2.1) and (2.2), the LT coefficients of the  $(a_0, a_1, b_1, c_{11})$  can be uniquely determined from moments as follows

$$(a_0, a_1) = \left( \frac{r_1^2 - r_2}{r_2^2 - r_1 r_3}, \frac{r_1 r_2 - r_3}{r_2^2 - r_1 r_3} \right),$$

$$b_1 = \frac{2r_1 r_2 - r_1^3 - r_3}{r_2^2 - r_1 r_3}, \quad c_{11} = a_1^2 - 2a_0 a_1 r_1 + a_0^2 r_{11}$$

of which details can be found in Kim (2016, 2017).

For the inversion of the marginal and joint LTs, we consider the case of distinct eigenvalues and the case of identical eigenvalues separately. First, Let  $X$  and  $Y$  be the random variables representing two consecutive stationary intervals of a MAP(2).

#### 3.1 Distinct eigenvalues

If  $(-D_0)^{-1}$  has distinct eigenvalues, then  $(-1/\nu_1, -1/\nu_2)$  can be determined as roots of the characteristic polynomial equation given as  $s^2 + a_1 s + a_0 = 0$ . Assuming, WLOG, that  $\nu_1 > \nu_2$ , we have

$$(\nu_1, \nu_2) = \left( \frac{a_1 + \sqrt{a_1^2 - 4a_0}}{2a_0}, \frac{a_1 - \sqrt{a_1^2 - 4a_0}}{2a_0} \right),$$

and

$$(\nu_3, \nu_4) = \left( \frac{r_1(\nu_1 + \nu_2) - r_{11} - \nu_1 \nu_2}{(r_1 - \nu_2)(\nu_1 - \nu_2)}, \frac{r_1(\nu_1 + \nu_2) - r_{11} - \nu_1 \nu_2}{(r_1 - \nu_1)(\nu_2 - \nu_1)} \right)$$

by moment matching based on Eq. (2.3). Again, by moment matching, the following equations can be obtained to write the marginal and joint LTs in (2.1) and (2.2) in terms of  $(\nu_1, \nu_2, \nu_3, \nu_4)$

$$(a_0, a_1, b_1) = \left( \frac{1}{\nu_1 \nu_2}, \frac{\nu_1 + \nu_2}{\nu_1 \nu_2}, \frac{\nu_1 \nu_3 + \nu_2 \nu_4}{\nu_1 \nu_2 (\nu_3 + \nu_4)} \right),$$

$$c_{11} = \frac{\nu_1^2 \nu_3 (1 - \nu_4) + \nu_2^2 \nu_4 (1 - \nu_3) + 2\nu_1 \nu_2 \nu_3 \nu_4}{\nu_1^2 \nu_2^2 (\nu_3 + \nu_4)}.$$

By inversion of the LT in (2.1) and (2.2) given in terms of  $(\nu_1, \nu_2, \nu_3, \nu_4)$ , we get the following marginal and lag-1 joint density functions

$$f(x) = \frac{\phi_1}{\nu_1} e^{-x/\nu_1} + \frac{1 - \phi_1}{\nu_2} e^{-x/\nu_2} \quad (3.1)$$

$$f(x, y) = \frac{\phi_{1,1}}{\nu_1^2} e^{-(x+y)/\nu_1} + \frac{\phi_{1,2}}{\nu_1 \nu_2} e^{-x/\nu_1 - y/\nu_2} \quad (3.2)$$

$$+ \frac{\phi_{2,1}}{\nu_2} \nu_1 e^{-x/\nu_2 - y/\nu_1} + \frac{\phi_{2,2}}{\nu_2^2} e^{-(x+y)/\nu_2}$$

where

$$(\phi_1, \phi_2) = \left( \frac{\nu_4}{\nu_3 + \nu_4}, \frac{\nu_3}{\nu_3 + \nu_4} \right), \quad \phi_{1,1} = \frac{\nu_4(1 - \nu_3)}{\nu_3 + \nu_4},$$

$$\phi_{1,2} = \phi_{2,1} = \frac{\nu_3 \nu_4}{\nu_3 + \nu_4}, \quad \phi_{2,2} = \frac{\nu_3(1 - \nu_4)}{\nu_3 + \nu_4}.$$

Note that  $(\phi_1, \phi_2) = (\phi_{11} + \phi_{12}, \phi_{21} + \phi_{22})$ . Depending on the sign of  $\nu_3$ , the marginal distribution of a stationary interval is either hyper-exponential or mixed generalized Erlang (MGE). In order to simplify the notation, let  $u_1(x)$  and  $u_2(x)$  be the exponential density function each with mean  $\nu_1$  and  $\nu_2$  respectively, i.e.

$$u_1(x) = \frac{1}{\nu_1} e^{-x/\nu_1}, \quad u_2(x) = \frac{1}{\nu_2} e^{-x/\nu_2}$$

Also, let  $u_{12}(x)$  be the density function of the hypo-exponential distribution that is a sum of two independent exponential random variables each with mean  $\nu_1$  and  $\nu_2$ , i.e.

$$u_{12}(x) = \frac{e^{-x/\nu_1}}{\nu_1 - \nu_2} + \frac{e^{-x/\nu_2}}{\nu_2 - \nu_1}$$

Below, we denote this hypo-exponential distribution by Hypoexp $(1/\nu_1, 1/\nu_2)$ .

(1) Hyper-exponential distribution:  $\nu_3 > 0$

If  $\nu_3 > 0$ , then we have  $\phi_1 > 0, \phi_2 > 0$ . Since  $\phi_1 + \phi_2 = 1$ , the marginal distribution of a stationary interval in (3.1) can be rewritten as

$$f(x) = \phi_1 u_1(x) + \phi_2 u_2(x)$$

and therefore  $X$  is a hyper-exponential, i.e.

$$X \sim \begin{cases} \text{Exp}(1/\nu_1) & \text{w.p. } \phi_1 \\ \text{Exp}(1/\nu_2) & \text{w.p. } \phi_2 \end{cases} \quad (3.3)$$

The joint density function (3.2) can be written as

$$f(x, y) = \phi_{1,1} u_1(x) u_1(y) + \phi_{1,2} u_1(x) u_2(y) \\ + \phi_{2,1} u_2(x) u_1(y) + \phi_{2,2} u_2(x) u_2(y).$$

By the definition of conditional probability, the conditional density function is given as

$$f(y|x) = \left( \frac{\phi_{1,1}u_1(x) + \phi_{2,1}u_2(x)}{\phi_1u_1(x) + \phi_2u_2(x)} \right) u_1(y) + \left( \frac{\phi_{1,2}u_1(x) + \phi_{2,2}u_2(x)}{\phi_1u_1(x) + \phi_2u_2(x)} \right) u_2(y)$$

by which the conditional distribution of  $Y$  given  $X$  is again hyper-exponential. That is, If  $X \sim \text{Exp}(1/\nu_1)$ , then the conditional distribution of  $Y$  is

$$(Y|X \sim \text{Exp}(1/\nu_1)) \sim \begin{cases} \text{Exp}(1/\nu_1) & \text{w.p. } \phi_{1,1}/\phi_1 \\ \text{Exp}(1/\nu_2) & \text{w.p. } \phi_{1,2}/\phi_1 \end{cases} \quad (3.4)$$

Otherwise, if  $X \sim \text{Exp}(1/\nu_2)$ , then the conditional distribution of  $Y$  is

$$(Y|X \sim \text{Exp}(1/\nu_2)) \sim \begin{cases} \text{Exp}(1/\nu_1) & \text{w.p. } \phi_{2,1}/\phi_2 \\ \text{Exp}(1/\nu_2) & \text{w.p. } \phi_{2,2}/\phi_2 \end{cases} \quad (3.5)$$

(2) MGE(2):  $\nu_3 < 0$

If  $\nu_3 < 0$ , then we have  $\phi_1 > 0, \phi_2 < 0$  and the marginal distribution in (3.1) is not hyper-exponential. By a simple manipulation, however, it can be shown that the marginal distribution is a mixed generalized Erlang, i.e.

$$f(x) = \psi_1 u_1(x) + \psi_{12} u_{12}(x)$$

where

$$(\psi_1, \psi_{12}) = \left( \phi_1 + \phi_2 \frac{\nu_1}{\nu_2}, \phi_2 - \phi_2 \frac{\nu_1}{\nu_2} \right) = \left( \frac{\nu_1 \nu_3 + \nu_2 \nu_4}{\nu_2 (\nu_3 + \nu_4)}, \frac{(\nu_2 - \nu_1) \nu_3}{\nu_2 (\nu_3 + \nu_4)} \right).$$

That is,

$$X \sim \begin{cases} \text{Exp}(1/\nu_1) & \text{w.p. } \psi_1 \\ \text{Hyperexp}(1/\nu_1, 1/\nu_2) & \text{w.p. } \psi_{12} \end{cases} \quad (3.6)$$

The joint density function is written as

$$f(x, y) = \psi_{1,1} u_1(x) u_1(y) + \psi_{1,12} u_1(x) u_{12}(y) + \psi_{12,1} u_{12}(x) u_1(y) + \psi_{12,12} u_{12}(x) u_{12}(y)$$

where

$$\psi_{1,1} = \phi_{1,1} + (\phi_{1,2} + \phi_{2,1}) \frac{\nu_1 \nu_2}{\nu_2^2} + \phi_{2,2} \frac{\nu_1^2}{\nu_2^2},$$

$$\psi_{1,12} = \left( \frac{\nu_2 - \nu_1}{\nu_2^2} \right) (\nu_2 \phi_{1,2} + \nu_1 \phi_{2,2}),$$

$$\psi_{12,1} = \left( \frac{\nu_2 - \nu_1}{\nu_2^2} \right) (\nu_2 \phi_{2,1} + \nu_1 \phi_{2,2}),$$

$$\psi_{12,12} = \frac{(\nu_1 - \nu_2)^2}{\nu_2^2} \phi_{2,2}.$$

By the definition of conditional probability, the conditional density function is given as

$$f(y|x) = \left( \frac{\psi_{1,1}u_1(x) + \psi_{12,1}u_{12}(x)}{\phi_1u_1(x) + \phi_{12}u_{12}(x)} \right) u_1(y) + \left( \frac{\psi_{1,12}u_1(x) + \psi_{12,12}u_{12}(x)}{\psi_1u_1(x) + \psi_{12}u_{12}(x)} \right) u_{12}(y)$$

by which the conditional distribution of  $Y$  given  $X$  is either exponential or hypo-exponential. That is, if  $X \sim \text{Exp}(1/\nu_1)$ , then the conditional distribution of  $Y$  is

$$(Y|X \sim \text{Exp}(1/\nu_1)) \sim \begin{cases} \text{Exp}(1/\nu_1) & \text{w.p. } \psi_{1,1}/\psi_1 \\ \text{Hyperexp}(1/\nu_1, 1/\nu_2) & \text{w.p. } \psi_{1,12}/\psi_1 \end{cases} \quad (3.7)$$

or if  $X \sim \text{Hypoexp}(1/\nu_1, 1/\nu_2)$ , then the conditional distribution of  $Y$  is

$$(Y | X \sim \text{Hyperexp}(1/\nu_1, 1/\nu_2)) \sim \begin{cases} \text{Exp}(1/\nu_1) & \text{w.p. } \psi_{12,1}/\psi_1 \\ \text{Hyperexp}(1/\nu_1, 1/\nu_2) & \text{w.p. } \psi_{12,12}/\psi_1 \end{cases} \quad (3.8)$$

### 3.2 Identical Eigenvalues

If  $(-D_0)^{-1}$  has identical eigenvalues, i.e.  $\nu_1 = \nu_2$ , then we have  $a_1^2 = 4a_0$  in Eq. (2.1) and we have  $\nu_1 = a_1/2$  and

$$(\nu_3, \nu_4) = \left( \frac{r_{11} - r_2(1 - r_1 + \nu_1)}{(r_1 - \nu_1)^2}, \frac{r_{11} - r_2}{r_1 - \nu_1} \right)$$

along with

$$(a_0, a_1, b_1) = \left( \frac{1}{\nu_1^2}, \frac{2}{\nu_1}, \frac{1}{\nu_1} \left( 1 - \frac{\nu_4}{\nu_1(\nu_3 + \nu_4)} \right) \right),$$

$$c_{11} = \frac{1}{\nu_1^2} \left( 1 - \frac{(2\nu_1 - \nu_4)\nu_4}{\nu_1^2(\nu_3 + \nu_4)} \right).$$

Let  $u_{11}(x)$  be the density function of the Erlang(2,  $1/\nu_1$ ) distribution that is a sum of two independent and identical exponential random variables with mean  $\nu_1$  i.e.

$$u_{11}(x) = \frac{xe^{-x/\nu_1}}{\nu_1^2}.$$

Then, by inverse LT, the marginal LT in Eq. (2.1) is converted into the following marginal density function

$$f(x) = \psi_1 u_1(x) + \psi_{11} u_{11}(x)$$

where  $(\psi_1, \psi_{11}) = (1 - \phi_1/\nu_1, \phi_1/\nu_1)$ . That is,

$$X \sim \begin{cases} \text{Exp}(1/\nu_1) & \text{w.p. } \psi_1 \\ \text{Erlang}(2, 1/\nu_1) & \text{w.p. } \psi_{11} \end{cases} \quad (3.9)$$

The joint LT given in Eq. (2.2), by inverse LT, is converted into the following joint density function.

$$f(x, y) = \psi_{1,1} u_1(x) u_1(y) + \psi_{1,11} u_1(x) u_{11}(y) + \psi_{11,1} u_{11}(x) u_1(y) + \psi_{11,11} u_{11}(x) u_{11}(y)$$

where

$$\begin{aligned} \psi_{1,1} &= \phi_{1,1} + (\phi_{1,2} + \phi_{2,1}) \frac{\nu_1 \nu_2}{\nu_2^2} \\ &+ \phi_{2,2} \frac{\nu_1^2}{\nu_2^2}, \psi_{1,11} = \left( \frac{\nu_2 - \nu_1}{\nu_2^2} \right) (\nu_2 \phi_{1,2} + \nu_1 \phi_{2,2}), \\ \psi_{11,1} &= \left( \frac{\nu_2 - \nu_1}{\nu_2^2} \right) (\nu_2 \phi_{2,1} + \nu_1 \phi_{2,2}), \\ \psi_{11,11} &= \frac{(\nu_1 - \nu_2)^2}{\nu_2^2} \phi_{2,2}. \end{aligned}$$

By the definition of conditional probability, the conditional density function is given as

$$\begin{aligned} f(y|x) &= \left( \frac{\psi_{1,1} u_1(x) + \psi_{11,1} u_{11}(x)}{\psi_1 u_1(x) + \psi_{11} u_{11}(x)} \right) u_1(y) \\ &+ \left( \frac{\psi_{1,11} u_1(x) + \psi_{11,11} u_{11}(x)}{\psi_1 u_1(x) + \psi_{11} u_{11}(x)} \right) u_{11}(y) \end{aligned}$$

by which the conditional distribution of  $Y$  given  $X$  is either exponential or Erlang. That is,

$$(Y|X \sim \text{Exp}(1/\nu_1)) \sim \begin{cases} \text{Exp}(1/\nu_1) & \text{w.p. } \psi_{1,1}/\psi_1 \\ \text{Erlang}(2, 1/\nu_1) & \text{w.p. } \psi_{1,11}/\psi_1 \end{cases} \quad (3.10)$$

or if  $X \sim \text{Erlang}(2, 1/\nu_1)$ , then the conditional distribution of  $Y$  is

$$(Y|X \sim \text{Erlang}(2, 1/\nu_1)) \sim \begin{cases} \text{Exp}(1/\nu_1) & \text{w.p. } \psi_{11,1}/\psi_{11} \\ \text{Erlang}(2, 1/\nu_1) & \text{w.p. } \psi_{11,11}/\psi_{11} \end{cases} \quad (3.11)$$

## 4. Numerical Exmples

### 4.1 Distinct Eigenvalues: $\nu_1 \neq \nu_2$

(1) Hyperexponential Distribution:  $\nu_3 > 0$

Consider a MAP(2) with the following set of moments  $(r_1, r_2, r_3, r_{11}) = (5/21, 17/294, 39/2744, 67/1176)$  for which we have  $(a_0, a_1, b_1, c_{11}) = (28, 11, 13/3, 19)$ ,  $(\nu_1, \nu_2) = (1/4, 1/7)$ , and  $(\nu_3, \nu_4) = (1/12, 2/3)$ . Since  $(\phi_1, \phi_2) = (8/9, 1/9)$ , the marginal distribution is hyper-exponential which can be generated as follows

$$X \sim \begin{cases} \text{Exp}(4) & \text{w.p. } 8/9 \\ \text{Exp}(7) & \text{w.p. } 1/9 \end{cases}$$

by Eq. (3.3). Since  $(\phi_{11}, \phi_{12}, \phi_{21}, \phi_{22}) = (22/27, 2/27, 2/27, 1/27)$ , the next interval  $Y$  can be generated conditional to the distribution of  $X$ , i.e.

$$(Y|X \sim \text{Exp}(4)) \sim \begin{cases} \text{Exp}(4) & \text{w.p. } 11/12 \\ \text{Exp}(7) & \text{w.p. } 1/12 \end{cases}$$

or

$$(Y|X \sim \text{Exp}(7)) \sim \begin{cases} \text{Exp}(4) & \text{w.p. } 2/3 \\ \text{Exp}(7) & \text{w.p. } 1/3 \end{cases}$$

by Eqs. (3.4) and (3.5). The next interval is generated conditional to the distribution of  $Y$ .

(2) MGE(2):  $\nu_3 < 0$

Consider a MAP(2) with the following set of moments  $(r_1, r_2, r_3, r_{11}) = (3/5, 1/3, 8/45, 16/45)$  for which we have  $(a_0, a_1, b_1, c_{11}) = (6, 5, 7/5, 9/5)$ ,  $(\nu_1, \nu_2) = (1/2, 1/3)$ , and  $(\nu_3, \nu_4) = (-1/2, 4/3)$ . Since  $(\phi_1, \phi_2) = (8/5, -3/5)$ , the marginal distribution is MGE(2) which can be generated as follows

$$X \sim \begin{cases} \text{Exp}(2) & \text{w.p. } 7/10 \\ \text{Hyperexp}(2, 3) & \text{w.p. } 3/10 \end{cases}$$

by Eq. (3.6). Since  $(\psi_{1,1}, \psi_{1,12}, \psi_{12,1}, \psi_{12,12}) = (9/20, 1/4, 1/4, 3/10)$ , the next interval  $Y$  can be generated conditional to the distribution of  $X$ , i.e.

$$(Y|X \sim \text{Exp}(2)) \sim \begin{cases} \text{Exp}(2) & \text{w.p. } 9/14 \\ \text{Hyperexp}(2, 3) & \text{w.p. } 5/14 \end{cases}$$

or

$$(Y|X \sim \text{Hyperexp}(2, 3)) \sim \begin{cases} \text{Exp}(2) & \text{w.p. } 5/6 \\ \text{Hyperexp}(2, 3) & \text{w.p. } 1/6 \end{cases}$$

by Eqs. (3.7) and (3.8). The next interval is generated conditional

to the distribution of  $Y$ .

#### 4.2 Identical Eigenvalues: $\nu_1 = \nu_2$

Consider a MAP(2) with the following set of moments  $(r_1, r_2, r_3, r_{11}) = (3/7, 11/63, 13/189, 103/567)$  for which we have  $(a_0, a_1, b_1, c_{11}) = (9, 6, 15/7, 31/7)$ ,  $(\nu_1, \nu_2) = (1/3, 1/3)$ , and  $(\nu_3, \nu_4) = (-1/2, 4/3)$ . We have  $(\phi_1, \phi_2) = (19/27, 2/27)$  and the marginal distribution is MGE(2) which can be generated as follows

$$X \sim \begin{cases} \text{Exp}(3) & \text{w.p. } 5/7 \\ \text{Erlang}(2,3) & \text{w.p. } 2/7 \end{cases}$$

by Eq. (3.9). Since  $(\psi_{1,1}, \psi_{1,12}, \psi_{12,1}, \psi_{12,12}) = (31/63, 14/63, 14/63, 4/63)$ , the next interval  $Y$  can be generated conditional to the distribution of  $X$ , i.e.

$$(Y|X \sim \text{Exp}(3)) \sim \begin{cases} \text{Exp}(3) & \text{w.p. } 31/45 \\ \text{Erlang}(2,3) & \text{w.p. } 14/45 \end{cases}$$

or

$$(Y|X \sim \text{Erlang}(2,3)) \sim \begin{cases} \text{Exp}(3) & \text{w.p. } 7/9 \\ \text{Erlang}(2,3) & \text{w.p. } 2/9 \end{cases}$$

by Eqs. (3.10) and (3.11). The next interval is generated conditional to the distribution of  $Y$ .

## 5. Conclusions

The one-to-one correspondence between the minimal set of moments and the minimal LT representation enables us to find a joint distribution function of the stationary intervals of a MAP( $n$ ) by linear transformation from moments to minimal LT and then by inversion of the LT. By simple algebraic manipulation of the inverse LT a joint distribution can be obtained by which a MAP can be generated without transition rate matrices. The presented analytic procedure is only for MAP(2)s of which canonical form is known for transformation from moments to the Markovian representation. However, no canonical transformation is available for MAPs of order 3 or higher for which a generalization of our approach can be useful in modeling and simulating a queueing

system with a MAP. Unlike the MAP(2) whose eigenvalues are always real valued, higher order MAPs may have complex-valued eigenvalues in which case the MAP can be represented as a repetition of a real-valued MAP. A natural direction of future research is the study of MAPs with cyclic Markov chain and trigonometric distribution function due to complex eigenvalues.

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